



10 Nm| MODULATING CONTROL / MODBUS RTU



## MEBA...10 (S1) SERIES

MEBA series electronic return valve actuators are especially designed and produced for applications in the HVAC systems. Our wide range of standard valve actuators has been developed to operate and position ball valves of different sizes.

Electronic Return® (ER) is able to manage short voltage interruptions for max. 4 seconds. In case of longer voltage interruption actuator will move the damper or valve to a predefined emergency position (EPS).

Torque: 10 Nm
Valve size DN40(1½") / DN50(2")
Power supply 24V <sub>AC/DC</sub>
Control Modulating 0(2)10 V <sub>DC</sub> / MODBUS RTU
Shaft dimension – 9 mm square (fixed)
Direction of rotation selectable by switch
Actuator with 1 m connection cable
Optional 1 adjustable SPDT auxiliary switch
 )

The appearance of the product may differ from the illustration. Technical specifications are subject to change.

MODEL SELECTION TABLE								
Model/type	Torque	Power supply	Running time	Emergency function	Auxiliary switch			
MEBA 1-10	10 Nm	$24 V_{AC/DC} \pm 10\%$	6570 s	40 s	-			
MEBA 1-10S1	10 Nm	$24~V_{AC/DC}\pm10\%$	6570 s	40 s	1 x SPDT (adjustable)			





## **MEBA – BALL VALVE ELECTRONIC RETURN ACTUATOR** 10 Nm| MODULATING CONTROL / MODBUS RTU



#### **TECHNICAL SPECIFICATION**

	MEBA 1-10 (S1)			
Torque	10 Nm			
Valve size	DN40(1½") / DN50(2")			
Shaft dimensions	□ 9.0 mm (fixed)			
Power supply	24 V <sub>AC/DC</sub> ± 10%			
Frequency	5060Hz			
Communication Baud rate ; STOP bits; parity ; address	MODBUS RTU 2400/4800/9600/19200/38400/57600/115200 ; 1 / 2 ; EVEN/ODD/NONE ; 1-247 – default (9600 ; 1 ; NONE ; 19)			
Control signal (input) – optional	0(2)10 V <sub>DC</sub>			
Position signal (output) – optional	010 V <sub>DC</sub>			
Power consumption				
In operation	6.0 W			
End position	2.0 W			
Rated power	6.5 VA			
Electrical connections	Cable 1 m			
Auxiliary switch rating	3 (1.5) A / 250 V <sub>AC</sub>			
Protection class	Class III			
Angle of rotation	90° (95° mechanical limitation)			
Weight	<1.0 kg			
Durability	60,000 rotations			
Sound level	45 dB			
IP protection class	IP54			
Working temperature range	-20°C50°C as per IEC 721-3-3			
Storage temperature	-30°C+60°C / IEC 721-3-2			
Ambient humidity	595% rH (non condensing) / EN			
Maintenance	Maintenance free			
Principle of operation	Type 1 (acc. to EN 60730-1)			
Electromagnetic compatibility	CE, UL 873 & ISO 9000 EN / EEC			

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#### Version o request MEBA...10 (S1)

Additional control signal (analogue) Input resistance for additional control signal Additional position signal Optional fixed termination resistor for MODBUS 0...10 Vpcor 2...10 Vpc Ri 100 kOhm or 500 kOhm 0...10 Vpc 120 Ohm

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#### MODBUS transmission parameters

The actuator has the following default (factory) settings of transmission parameters:

- ID address: 19 decimal = 13 hex
- Baud rate number of data bits parity number of stop bits = 19200 8 None 1

To change the above settings, use the MODBUS CONFIGURATOR device manufactured by NENUTEC.

Adr	R/W	Name	Values	Default	Description	Notes
0	RW	SET_POINT	0 ÷ 100	100	Set point [%]	1)
1	RW	OVERRIDE	0 ÷ 5	0	0 – normal operation / the actuator moves to SET_POINT 1 – ignore SET_POINT and stop / lock position , 2 – ignore SET_POINT and move to 0% 3 – ignore SET_POINT and move to 100% 4 – ignore SET_POINT and move to LOW_LIM, 5 – ignore SET_POINT and move to HIGH_LIM.	2)
2	R	rsv	0x0000	0x0000	reserved	
3	R	EXT_POW	0 ÷ 2		0 – no external power supply 1 – external power supply present 2 – connected to the MODBUS CONFIGURATOR device	
4	R	DAMPER_POS	0 ÷ 100	0 ÷ 100	Current position (momentary) [%]	
5	R	BAT_CHARGE	0 ÷ 100	0 ÷ 100	Battery charge level [%]	
6	R	DIRECTION	0 / 1	0 / 1	0 – clockwise (CW) / 1 – counter-clockwise (CCW)	
100	_					
100	R	DEV_ID	0x202C	-	Device ID (actuator with safety function)	
101	R	rsv	0x0000	0x0000	reserved	
102	R	rsv	0x0000	0x0000	reserved	
103	R	SOFT_VER	0 ÷ 0x9999	-	Firmware version (eg. 0x3210 indicates version 3.21a)	3)
104	R	STATUS	0 ÷ 2, 10, 20	_	<ul> <li>0 - no error, actuator in position according to the control signa</li> <li>1 - no error, actuator moves to the position according to the control signal</li> <li>2 - no error, no movement, battery charging</li> <li>10 - motor current exceeding limit, retry movement to the position according to the control signal</li> <li>20 - motor current exceeding limit, the position according to the control signal not reached</li> </ul>	
105	RW	LOW_LIM	0 ÷ 100	0		4)
106	RW	HIGH_LIM	0 ÷ 100	100		1
107	RW	rsv	0x0000	0x0000	reserved	
108	RW	BUS_FAIL_POS	0÷100, 200	200	Position in case of communication loss (bus fail position)	5)
109	RW	SETPOINT_INIT	0 ÷ 100, 200	100	SET_POINT initial value (after switching on the power or reset)	1)
110	RW	WR_UNLOCK	0x0000 / 0xC5A3 / 0x6781	0x0000	0x0000 – write / change NV registers not allowed, 0xC5A3 – change NV registers allowed, 0x6781 – write NV registers.	





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#### NOTES:

- R read register; W write register; RW read & write register
  - 1. SET POINT initial value is taken from the volatile register SETPOINT INIT.
  - A value in the range 0-100 means the actuator reached the set position. The value 200 in SETPOINT\_INIT register means automatic copying of VREG value (0..10 V or 2..10 V control input) to the SET\_POINT register (this means control via VREG analogue input).
  - 2. Writing to OVERRIDE register (address 1) doesn't change the SET\_POINT value (address 0).
  - 3. STATUS = 10 means that the actuator encounters increased mechanical resistive force and makes repeated attempts to move to the set position.

STATUS = 20 means that the actuator encounters increased mechanical resistive force and stopped movement after 5 attempts to reach the set position (failure).

- Each writing in SET\_POINT or OVERRIDE register resets STATUS and restarts the movement to set position.
- 4. LOW\_LIM and HIGH\_LIM registers limit range of actuator movement to LOW\_LIM (lower limit) and HIGH\_LIM (upper limit) values, respectively.
- In addition, the following conditions must be fulfilled: 0% <= LOW\_LIM and LOW\_LIM+30% <= HIGH\_LIM <=100% (minimum range of movement 30%).
- 5. BUS\_FAIL\_POS contains actuator position in the case of MODBUS communication failure (after 120 sec. form the loss of communication).

The value BUS\_FAIL\_POS = 200 deactivates this function (the actuator doesn't react to loss of communication).

#### Changing device settings

All registers with address 100-109 are non-volatile (NV). If WR\_UNLOCK = 0x0000, an attempt to change the value of the NV registers will have no effect.

After writing WR\_UNLOCK = 0xC5A3, it is possible to change values in NV registers, but their new values are not yet taken into account. After writing WR\_UNLOCK = 0x6781, the new values of NV registers are written to non-volatile memory and taken into account for operation of the device.





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#### ▲ IMPORTANT REMARKS

This actuator includes electrical and electronic components and may not be disposed as household waste. Please consider the local valid legislation.

24 V<sub>AC/DC</sub>: Connect via safety isolating transformer.

 $230 \ V_{AC}: \qquad \mbox{To isolate from the main power supply, the system must incorporate a device which disconnects the phase conductor (with at least a 3mm contact gap.)}$ 

Consult NENUTEC representatives for specific requirements and material selections for your intended application. The entire content of this technical datasheet is protected by copyright. All rights are reserved ©.

The performance specifications are nominal and conform to acceptable industry standards. Nenutec shall not be liable for damages resulting from misapplication or misuse of its products.

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#### **CUSTOMISED VERSION**

NENUTEC offers you actuators in customised versions, e.g. with your own brand name, with colourcoordinated applications and with your particular demand on request.

For further information please contact us or our local representative.